

SIGNALS & SYSTEMS

Complete Multipage Master Handbook & Problem Solver | GATE ECE 2027

Target Exam:	GATE 2027 Electronics & Communication (EC)
Organizing Institute:	IIT Madras
Syllabus Standard:	100% Complete Syllabus + 2027 Revisions
Edition:	Comprehensive Multipage Textbook & Problem Solver

TABLE OF CONTENTS

Chapter 1: Continuous & Discrete Signal Fundamentals	Page 3
Chapter 2: LTI Systems & Convolution	Page 4
Chapter 3: Fourier Transforms & Laplace/Z Transforms	Page 5
Chapter 4: Nyquist Sampling & Signal Reconstruction	Page 6
Chapter 5: FIR and IIR Digital Filter Design	Page 7

CHAPTER 1: CONTINUOUS & DISCRETE SIGNAL FUNDAMENTALS

1.1 Signal Classification & Energy/Power

Signals are classified based on energy, power, periodicity, and symmetry.

- **Energy Signal:** $0 < E < \infty$ and Power $P = 0$. Energy $E = \int |x(t)|^2 dt$.
- **Power Signal:** $0 < P < \infty$ and Energy $E = \infty$.
- **Even Signal:** $x(-t) = x(t)$ (Real & even Fourier transform).
- **Odd Signal:** $x(-t) = -x(t)$ (Imaginary & odd Fourier transform).

CHAPTER 2: LTI SYSTEMS & CONVOLUTION

2.1 Continuous & Discrete Convolution

LTI systems are completely characterized by their impulse response $h(t)$.

- **Continuous Convolution:** $y(t) = \int x(\tau) h(t - \tau) d\tau$.
- **Discrete Convolution:** $y(n) = \sum x(k) h(n - k)$.
- **Length Rule:** If $x(n)$ has length L and $h(n)$ has length M , output $y(n)$ has length $N_y = L + M - 1$.

CHAPTER 3: FOURIER TRANSFORMS & LAPLACE/Z TRANSFORMS

3.1 Transform Properties & ROC Rules

Transforms convert time-domain differential/difference equations into algebraic equations.

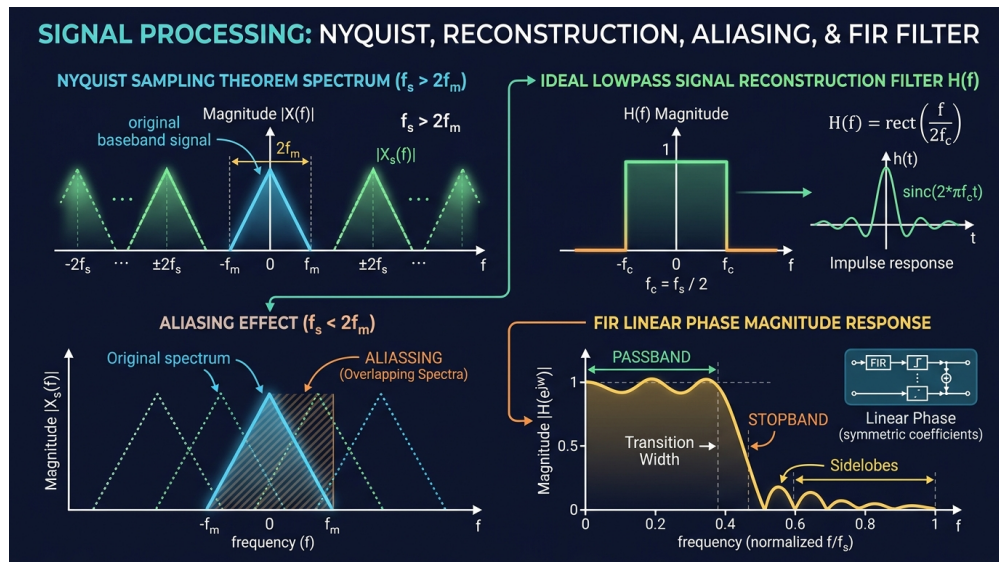
- **Laplace ROC:** Contains no poles. Stable if ROC contains $j\omega$ axis.
- **Z-Transform ROC:** Stable if ROC contains unit circle $|z| = 1$.

CHAPTER 4: NYQUIST SAMPLING & SIGNAL RECONSTRUCTION

4.1 Nyquist Theorem & Ideal Reconstruction Filter (GATE 2027 Focus)

A continuous signal $x(t)$ band-limited to f_m Hz can be perfectly reconstructed if sampled at rate $f_s \geq 2 f_m$.

- **Nyquist Rate:** Minimum sampling rate $f_s = 2 f_m$.
- **Aliasing:** Occurs when $f_s < 2 f_m$, causing spectral overlap.
- **Reconstruction Formula:** $x(t) = \sum x(n T_s) \text{sinc}((t - n T_s)/T_s)$.



CHAPTER 5: FIR AND IIR DIGITAL FILTER DESIGN

5.1 FIR & IIR Filter Design Methods (NEW FOR GATE 2027)

Digital filter design is a major newly added topic in the GATE 2027 syllabus.

- **FIR Filters:** Always stable, exact linear phase when $h(n) = \pm h(N - 1 - n)$. Designed using Window methods (Rectangular, Hamming, Blackman).
- **IIR Filters & Bilinear Transformation (BLT):** Maps s-plane to z-plane using $s = (2/T_s) * (1 - z^{-1}) / (1 + z^{-1})$.
- **Frequency Pre-Warping:** $\Omega = (2/T_s) * \tan(\omega/2)$ to compensate for non-linear frequency compression.

WORKED GATE NUMERICAL: Bilinear Transformation Filter Pole

Problem: Convert analog filter $H_a(s) = 1 / (s + 5)$ to digital filter $H(z)$ using BLT with $T_s = 0.2$ s.

Step-by-Step Derivation & Solution:

1. Substitute $s = 10 * (z - 1) / (z + 1)$
2. $H(z) = 1 / [10(z-1)/(z+1) + 5] = (z+1) / (15z - 5) = (1/15) * (1 + z^{-1}) / (1 - (1/3)z^{-1})$
3. Digital Pole: $z = 1/3 = 0.333$ (Inside unit circle -> Stable).